

Newton's 1st Law

When viewed from an inertial reference frame, an object at rest will remain @ rest + an object in motion will remain @ a constant velocity unless acted upon by a net external force.

Inertial reference frame $a = 0$

non-inertial reference frame $a \neq 0$

mass – a measure of inertia.

Inertia – tendency of an object to resist an acceleration (change in state of motion)

Newton's 2nd Law: $\Sigma \vec{F} = m\vec{a}$ $N = \frac{kg \cdot m}{s^2}$

weight \neq mass

(force of gravity) vector vs scalar

extrinsic vs intrinsic property

$\vec{F}_g = \vec{W} = m\vec{g}$ down $g = 9.8 \text{ m/s}^2$

Video Lecture #2 – Example - Three Forces act on an Object, Finding Acceleration, Mass and Velocity

EX | $\vec{F}_1 = [2.00\hat{i} + 2.00\hat{j}] \text{ N}$

$\vec{F}_2 = (-1.00\hat{i} + 3.00\hat{j}) \text{ N}$

$\vec{F}_3 = (1.00\hat{i} - 3.00\hat{j}) \text{ N}$

$||a|| = 1.25 \text{ m/s}^2 \quad v_i = (5.00\hat{i}) \text{ m/s}$

a) direction of a ? c) v @ 15 s = ?

b) $m = ?$

$\Sigma \vec{F} = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 = (2 - 1 + 1)\hat{i} + (2 + 3 - 3)\hat{j} = (-1\hat{i} + 2\hat{j}) \text{ N}$

$a^2 + b^2 = c^2 \quad \Sigma F = \sqrt{2^2 + (-1)^2} = \sqrt{5} \text{ N}$

$\Sigma \vec{F} = m\vec{a} \quad \sqrt{5} = m(1.25) \quad m = 1.7889 \approx 1.79 \text{ kg}$

$\sin \theta = \frac{0}{H} = \frac{\Sigma F_y}{\Sigma F} \quad \theta = \sin^{-1}\left(\frac{2}{\sqrt{5}}\right) = 63.439^\circ = 63.4^\circ$

$v = v_i + a\Delta t \quad \vec{a} = ? \quad a = \frac{\Sigma F}{m} = \frac{-1 + 2j}{1.7889} \quad \vec{a} = (-0.559\hat{i} + 1.118\hat{j})$
above -x axis

$v(15) = 5\hat{i} + (-0.559\hat{i} + 1.118\hat{j})15 = 5\hat{i} - 8.385\hat{i} + 16.771\hat{j}$

$v(15) = (-3.39\hat{i} + 16.8\hat{j}) \text{ m/s}$

Video Lecture #3 – Newton's 3rd Law - AP Physics Version

$\vec{F}_{12} = -\vec{F}_{21}$ NEWTON'S THIRD LAW

Video Lecture #4 – Defining Normal Force and Tension

Normal Force $\rightarrow \perp$ to surface + a push

Tension Force \rightarrow rope, string...

in direction of rope + a pull

Video Lecture #5 – Introduction to Equilibrium

Thank You, Sarah Johnson, for these notes.

Equilibrium

$\Sigma \vec{F} = 0 = m\vec{a}$

$a = 0 = \frac{\Delta v}{\Delta t}$

It's not moving or @ constant velocity.

Video Lecture #6 – Introduction to Static and Kinetic Friction and the Coefficient of Friction

Friction:

static (not moving)

kinetic (in motion)

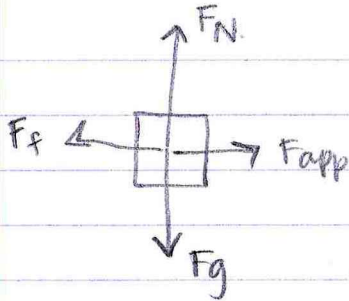
$$F_f = \mu F_N \quad \mu (\text{mm})$$

$$F_{kf} = \mu_k F_N \quad \text{coefficient of friction}$$

$$F_{sf} \leq \mu_s F_N \quad \text{dimensionless}$$

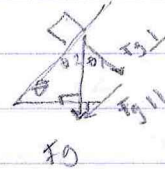
$$F_{sf \max} = \mu_s F_N \quad \text{Always opposes motion}$$

parallel to surface
independent of F_a



$$\mu_s > \mu_k$$

(except TENSION)



$$F_{g \parallel} = F_g \sin \theta = mg \sin \theta$$

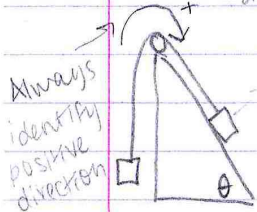
$$F_{g \perp} = F_g \cos \theta = mg \cos \theta$$

Video Lecture #7 & 8 – Chapter 05 #26

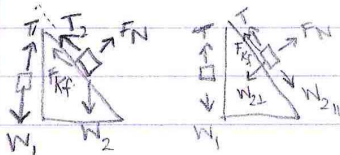
(Part 1) Reviewing Pulleys, Inclines and Free Body Diagrams with an Example Problem
(Part 2) Reviewing Pulleys, Inclines and Free Body Diagrams with an Example Problem

Ch. 5-26 $m_1 = 2.00 \text{ kg}$ $m_2 = 6.00 \text{ kg}$ $\theta = 55.0^\circ$

a) $a = ?$ b) $T = ?$ $\mu_k = 0.100$



$$T = T_1 = T_2 \quad (\text{pulley is massless})$$



$$\sum F_{\parallel} = -W_1 + T - T - F_{kf} + W_{2\parallel} = m a_{\parallel}$$

on whole thing $-m_1 g - \mu_k F_N + m_2 g \sin \theta = (m_1 + m_2) a_{\parallel}$

$$\sum F_{\perp} = F_N - W_{2\perp} = m_2 a_{\perp} = m_2 \cos \theta = 0$$

just on m_2 $F_N = W_{2\perp} = m_2 g \cos \theta$

$$-m_1 g - \mu_k m_2 g \cos \theta + m_2 g \sin \theta = (m_1 + m_2) a_{\parallel}$$

$$a_{\parallel} = \frac{-m_1 g - \mu_k m_2 g \cos \theta + m_2 g \sin \theta}{m_1 + m_2}$$

$$a_{\parallel} = \frac{-(2)(9.8) - (0.1)(6)(9.8) \cos(55) + (6)(9.8) \sin(55)}{(2) + (6)}$$

$$a_{\parallel} = 3.1491 \text{ m/s}^2 \approx 3.15 \text{ m/s}^2$$

$$\sum F_{\parallel} = T - W_1 = m_1 a_{\parallel}$$

on m_1

$$T = m_1 a_{\parallel} + W_1 = m_1 a_{\parallel} + m_1 g$$

$$T = m_1 (a_{\parallel} + g) = 2(3.1491 + 9.8)$$

$$T = 25.8982 \approx 25.9 \text{ N}$$

Video Lecture #9 – Introduction and Review of Centripetal Force

Circular Motion:

$$\sum F_{IN} = ma_c = m \frac{v^2}{r}$$

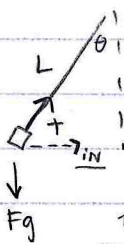
Centripetal force.

Draw FBD + $\sum F_{IN}$

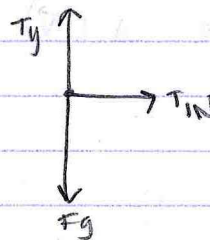
- Not a new force.
- never is an FBD.
- in is + (out is -)

Video Lecture #10 – A Conical Pendulum - A Classic Centripetal Force Example Problem

ex. Conical Pendulum.



know $L + \theta$
find $v_t = ?$



$$\sin \theta = \frac{r}{L} = \frac{T_{IN}}{T}$$

$$T_{IN} = T \sin \theta$$

$$\cos \theta = \frac{L_y}{L} = \frac{T_y}{T}$$

$$T_y = T \cos \theta$$

$$\sum F_y = T_y - F_g = ma_y = m(0) = 0$$

$$T_y = F_g = mg$$

$$T \cos \theta = mg \Rightarrow T = \frac{mg}{\cos \theta}$$

$$\sum F_{IN} = +T_{IN} = ma_c$$

$$T \sin \theta = m \frac{v_t^2}{r}$$



$$\sin \theta = \frac{r}{L} = \frac{r}{L}$$

$$r = L \sin \theta$$

$$r T \sin \theta = m v_t^2$$

$$v_t = \sqrt{\frac{r T \sin \theta}{m}}$$

$$v_t = \sqrt{\frac{L \sin \theta T \sin \theta}{m}} = \sqrt{\frac{L \sin^2 \theta \cancel{mg}}{\cancel{m} \cos \theta}}$$

$$v_t = \sqrt{\frac{L \sin^2 \theta g}{\cos \theta}}$$

Video Lecture #11 – Introduction to Non-Uniform Circular Motion

Non-uniform circular motion.

Have both $\sum F_t + \sum F_{IN}$

have both $a_t + a_c$

$$\sum F = \sum F_t + \sum F_{IN}$$

Video Lecture #12 – Introduction to Resistive Forces or the Force of Drag

6.4 Resistive Forces (proportional)

Force of Drag \propto to Velocity

$$\vec{R} = -b\vec{v} \quad (b \Rightarrow \text{proportionally constant kg/s})$$

(small objects @ small speeds)

$$R = \frac{1}{2} D \rho A v^2 \quad (\text{more generally applicable})$$

$D \Rightarrow$ Drag Coefficient. (no dim)

$\rho \Rightarrow$ Density of medium

$A \Rightarrow$ cross sectional area ($A \perp \vec{v}$)

$\vec{v} =$ velocity of object

Video Lecture #13 – Deriving the Equation for Terminal Velocity

ex. object in ~~free~~ air falling



$$\sum F_y = R - F_g = ma_y$$

$$\frac{1}{2} D \rho A v^2 - mg = ma_y$$

$$a_y = \frac{D \rho A v^2}{2m} - g$$

w/ no resistance force

$$a_y = -g$$

as $v \uparrow \Rightarrow R \uparrow \Rightarrow a \Rightarrow 0$

$$a = 0 \Rightarrow V = V_{\text{terminal}} = V_t$$

($R = F_g$)

NOT UAM

$$0 = \frac{D \rho A v^2}{2m} - g$$

$$g = \frac{D \rho A v^2}{2m}$$

$$V_t = \sqrt{\frac{2mg}{D \rho A}}$$

terminal velocity

Video Lecture #14 – Numerical Modeling - An Example Freefall Problem with Air Drag

Numerical Analysis

ex. Baseball Throw ball upward @ 50.0 m/s.

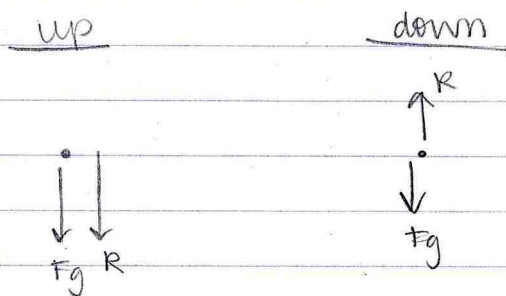
$m = 145 \text{ g}$

$r = 3.7 \text{ cm.}$

$D = 0.284$

up $\Sigma F_y = -R - F_g = ma_y$

down $\Sigma F_y = R - F_g = ma_y$



Video Lecture #16 – Chapter 06 #35 - An Introductory Drag Force Problem

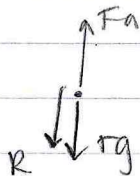
Ch. 6-35

copper ball $r = 2.00 \text{ cm.}$ $b = 0.95 \text{ kg/s}$

constant speed $v = 0.090 \text{ m/s}$

$D = 8.92 \times 10^3$

fluid.



$\Sigma F_y = F_a - R - F_g = ma_y$

$F_a - (bv) - mg = m(0) = 0$

$F_a = mg + bv$

$F_a = (0.2989)(9.81) + (0.95)(0.09)$

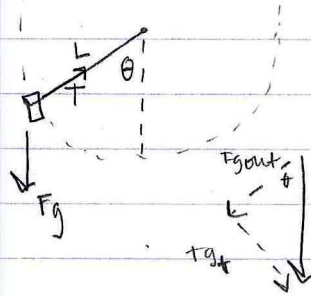
$F_a = 3.014 \text{ N} \approx \boxed{3.01 \text{ N}}$

$D = \frac{m}{v} \Rightarrow m = DV_{\text{sphere}} = D \frac{4}{3} \pi r^3$
 $m = (8920) \left(\frac{4}{3} \pi (0.02)^3 \right) = 0.2989 \text{ kg.}$

$R = bv$
direction.

Video Lecture #16 – Example Problem - A Stopper on a String moving in a Vertical Circle

ex. know $L, M, \theta, v = ?$



Tension is in the "in" direction.

$\sin \theta = \frac{r}{L} = \frac{F_{gt}}{F_g}$

$F_{gt} = mg \sin \theta$

$\cos \theta = \frac{A}{L} = \frac{F_{gout}}{F_g}$

$F_{gout} = mg \cos \theta$

$\Sigma F_t = F_{gt} = ma_t$

$mg \sin \theta = ma_t$

$g \sin \theta = a_t$

min v_t to keep in circle

@ top ... $\theta = 180^\circ$

$0 = mg \cos 180 + \frac{mv^2}{L}$

$mg = \frac{mv^2}{L}$

$v_t = \sqrt{gL}$

$\Sigma F_{in} = T - F_{gout} = ma_c$

$T - mg \cos \theta = m \frac{v_t^2}{r} = \frac{mv^2}{L}$

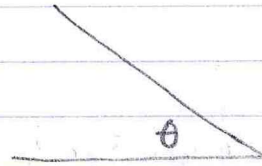
$T = mg \cos \theta + \frac{mv^2}{L}$

Review ch. 05 + Ch. 06.

Equilibrium

$$\sum \vec{F} = 0 = m\vec{a} \Rightarrow \vec{a} = 0$$

@ c.v. or not moving.



$$\sum F_{\perp} + \sum F_{\parallel}$$

F.B.D $\Rightarrow \sum F$

$$F_{kf} = \mu_k F_N$$

$$F_s \leq \mu_s F_N$$

$$(F_{sf} = \mu_s F_N)_{(max)}$$

identify + dir (Pulley)

- object(s)
- which direction.

When can you $\sum F$ on multiple objects?

$$\sum F_{whole} = m_t a$$

↑ same.

Circular motion

$$\sum F_{in} = ma_c = \frac{mv^2}{r}$$

- not a new force.
- never draw in FBD
- in is + (out is -)

* Note: $a_t \neq 0$ $a_c + a_t$

$$\vec{R} = -b\vec{v} \quad R = \frac{1}{2} D_p A v^2$$

$v_{terminal} \Rightarrow$